Ph.D. Preliminary Examination in Numerical Analysis Department of Mathematics New Mexico Institute of Mining and Technology August 12, 2019, 9 AM - 1 PM, Weir 202

- 1. This exam is four hours long.
- 2. You need a scientific calculator for this exam.
- 3. Work out all six problems.
- 4. Start the solution of each problem on a new page.
- 5. Number all of your pages.
- 6. Sign your name on the following line and put the total number of pages.
- 7. Use this sheet as a coversheet for your papers.

NAME: \_\_\_\_\_ No. of pages:\_\_\_\_\_

#### Problem 1.

Consider the function

$$F(x) = \tan^{-1}(x)$$

on an interval  $a \leq x \leq b$ , where 0 < a < b. Show that function F(x) is contractive on this interval and find the smallest value of  $\lambda$  such that

$$|F(x) - F(y)| \le \lambda |x - y|$$

for every x and y in the interval [a, b].

# Problem 2.

- a) Prove that unitarily similar matices have the same eigenvalues.
- b) Let A and B be unitarily similar matrices. Express eigenvectors of B in terms of eigenvectors of A.

## Problem 3.

Let A be  $m \times n$  real matrix,  $m \ge n$ , and let A have rank n. Let  $b \in \mathbb{R}^m$ . Prove the following statements:

- a) There exists unique  $x \in \mathbb{R}^n$  minimizing  $||Ax b||_2^2$ , where  $||\cdot||_2$  is the 2-norm.
- b) The matrix  $A^T A$  is invertible and  $x = (A^T A)^{-1} A^T b$ .

## Problem 4.

Find the constants  $c_0, c_1$  and  $x_1$  so that the quadrature formula

$$\int_0^1 f(x)dx = c_0 f(0) + c_1 f(x_1)$$

has the highest possible degree of precision. What is the degree of precision of the quadrature formula?

#### Problem 5.

- a) State the theorem on convergence of the fixed point iteration  $x_{n+1} = g(x_n)$  with a function g(x) defined on the interval [a, b].
- b) Let  $\{x_n\}$  be the convergent sequence generated by the fixed point iteration, let  $x_*$  be a fixed point of g(x), and let  $k = \max_{x \in [a,b]} |g(x)|$ . Give an estimate of the error  $|x_n x_*|$  in terms of k.
- c) Consider the function  $g(x) = x^2 + \frac{3}{16}$ . Find all fixed points of g(x).
- d) For each of the fixed points, explain why or why not the fixed point iteration with g(x) is guaranteed to converge. If fixed point iteration is guaranteed to converge, specify an interval [a, b] such that, for any initial guess  $x_0 \in [a, b]$ , the fixed point iteration produces a convergent sequence.

e) For each convergent fixed point iteration, determine how many iterations are required to reduce the error by a factor of 10.

# Problem 6.

- a) Describe the power method for computing the dominant eigenvalue and a corresponding eigenvector of a matrix.
- b) Find the eigenvalues and eigenvectors of the matrix

$$A = \left(\begin{array}{cc} 6 & 4\\ 4 & 6 \end{array}\right).$$

Is the matrix semi-simple (diagonalizable)? Does it have a dominant eigenvalue?

- c) Demonstrate convergence of the power method by performing four iterations on matrix A with the initial guess  $v = (1, 0)^T$ .
- d) Compute the relative errors of the obtained approximations using the  $\infty$ -norm.

# Solutions

## Problem 1.

Consider the function

$$F(x) = \tan^{-1}(x)$$

on an interval  $a \leq x \leq b$ , where 0 < a < b. Show that function F(x) is contractive on this interval and find the smallest value of  $\lambda$  such that

$$|F(x) - F(y)| \le \lambda |x - y|$$

for every x and y in the interval [a, b].

# Solution.

Take any two points x and y in [a, b]. Recall that the derivative of  $\tan^{-1}(x)$  is  $1/(1+x^2)$ . By the mean value theorem,

$$F(x) - F(y) = F'(\xi)(x - y)$$

for some  $\xi$  in the interval between x and y. Thus

$$|F(x) - F(y)| = (1/(1+\xi^2))|x - y|$$

Since the largest possible value of  $1/(1+\xi^2)$  occurs at  $\xi = a$ ,

$$|F(x) - F(y)| \le (1/(1+a^2))|x - y|$$

for every x and y in [a, b]. Note that  $1/(1 + a^2) < 1$ . Thus F is a contractive mapping on [a, b] and the best possible value of  $\lambda$  is  $1/(1 + a^2)$ .

## Problem 2.

- a) Prove that unitarily similar matices have the same eigenvalues.
- b) Let A and B be unitarily similar matrices. Express eigenvectors of B in terms of eigenvectors of A.

## Solution.

Let  $\lambda$  be any eigenvalue of A. Then

$$det(A - \lambda I) = 0.$$
$$det(Q) det(A - \lambda I) det(Q^*) = 0.$$
$$det(Q(A - \lambda I)Q^*) = 0.$$
$$det(QAQ^* - \lambda QQ^*) = 0.$$

But  $QQ^* = I$ , so

$$\det(QAQ^* - \lambda I) = 0.$$

Since  $B = QAQ^*$ ,

 $\det(B - \lambda I) = 0.$ 

Thus  $\lambda$  is an eigenvalue of B.

Conversely, if  $\lambda$  is an eigenvalue of B, then since

 $B = QAQ^*$ 

we have

$$Q^*BQ = A$$

By the same argument as above, if  $\lambda$  is an eigenvalue of B, then  $\lambda$  is an eigenvalue of A.

If v is an eigenvector of A with eigenvalue  $\lambda$ , then

$$Av = \lambda v$$
$$Q^* B Q v = \lambda v$$
$$B(Qv) = \lambda(Qv)$$

Thus Qv is an eigenvector of B with eigenvalue  $\lambda$ .

#### Problem 3.

Let A be  $m \times n$  real matrix,  $m \ge n$ , and let A have rank n. Let  $b \in \mathbb{R}^m$ . Prove the following statements:

- a) There exists unique  $x \in \mathbb{R}^n$  minimizing  $||Ax b||_2^2$ , where  $||\cdot||_2$  is the 2-norm.
- b) The matrix  $A^T A$  is invertible and  $x = (A^T A)^{-1} A^T b$ .

## Solution.

a) Let the SVD decomposition of A be  $A = U\Sigma V^T$ , where  $U \in \mathbb{R}^{m \times m}$  and  $V \in \mathbb{R}^{n \times n}$ are orthogonal matrices,  $\Sigma \in \mathbb{R}^{m \times n}$  has non-zero entries  $Sigma_{i,i} = \sigma_i$  (for  $i \leq n$ , where  $\sigma_i$  are the singular values).

$$||Ax - b||_{2}^{2} = ||U^{T}(Ax - b)||_{2}^{2} = ||U^{T}Ax - U^{T}b||_{2}^{2} = ||\Sigma(V^{T}x) - U^{T}b||_{2}^{2}$$

Let  $y = V^T x \in \mathbb{R}^n$  and  $c = U^T b \in \mathbb{R}^m$ , then

$$||Ax - b||_2^2 = ||\Sigma y - c||_2^2 = \sum_{i=1}^n |\sigma_i y_i - c_i|^2 + \sum_{i=n+1}^m |c_i|^2.$$

Therefore,  $||Ax - b||_2^2$  is minimized if and only if  $\sigma_i y_i - c_i = 0$  (i.e.,  $y_i = c_i / \sigma_i$ ) for i = 1, ..., n. Consequently, the solution x = Vy is uniquely determined.

b) First show the invertibility.

$$A^{T}A = V\Sigma^{T}U^{T}U\Sigma V^{T} = V\Sigma^{T}\Sigma V^{T}.$$
(1)

The matrix  $\Sigma^T \Sigma \in \mathbb{R}^{n \times n}$  is a diagonal matrix with all n non-zero main-diagonal entries  $\sigma_i^2$  (i = 1, ..., n), so it is invertible. Therefore,  $(A^T A)^{-1} = V(\Sigma^T \Sigma)^{-1}V$ . The least squares problem  $||Ax - b||_2^2$  is minimized if and only if  $Ax - b \in N(A^T)$  (i.e.,  $A^T(Ax - b) = 0$ ). Then the solution x satisfies  $A^T Ax = A^T b$ . Since  $A^T A$  is invertible, x can be solved as  $x = (A^T A)^{-1} A^T b$ .

# Problem 4.

Find the constants  $c_0, c_1$  and  $x_1$  so that the quadrature formula

$$\int_0^1 f(x)dx = c_0 f(0) + c_1 f(x_1)$$

has the highest possible degree of precision. What is the degree of precision of the quadrature formula?

# Solution.

Let f(x) = 1, then  $\int_0^1 1 dx = c_0 + c_1$ . Let f(x) = x, then  $\int_0^1 x dx = c_0 0 + c_1 x_1$ . Let  $f(x) = x^2$ , then  $\int_0^1 x^2 dx = c_0 0 + c_1 x_1^2$ . Simply the equations, we end up with

$$\begin{array}{rcl}
1 &=& c_0 + c_1 \\
\frac{1}{2} &=& c_1 x_1. \\
\frac{1}{3} &=& c_1 x_1^2.
\end{array}$$

The values of the constants are

$$c_0 = \frac{1}{4}, c_1 = \frac{3}{4}, x_1 = \frac{2}{3}.$$

#### Problem 5.

- a) State the theorem on convergence of the fixed point iteration  $x_{n+1} = g(x_n)$  with a function g(x) defined on the interval [a, b].
- b) Let  $\{x_n\}$  be the convergent sequence generated by the fixed point iteration, let  $x_*$  be a fixed point of g(x), and let  $k = \max_{x \in [a,b]} |g(x)|$ . Give an estimate of the error  $|x_n x_*|$  in terms of k.
- c) Consider the function  $g(x) = x^2 + \frac{3}{16}$ . Find all fixed points of g(x).
- d) For each of the fixed points, explain why or why not the fixed point iteration with g(x) is guaranteed to converge. If fixed point iteration is guaranteed to converge, specify an interval [a, b] such that, for any initial guess  $x_0 \in [a, b]$ , the fixed point iteration produces a convergent sequence.
- e) For each convergent fixed point iteration, determine how many iterations are required to reduce the error by a factor of 10.

## Solution.

#### Theorem.

Let g(x) be a continuously differentiable function on the interval [a, b] such that

$$g(x) \in [a, b], \ \forall x \in [a, b],$$

let  $k = \max_{x \in [a,b]} |g(x)|$ . If k < 1, then function g(x) has a unique fixed point  $x_* \in [a,b]$ , the fixed point iteration  $x_{n+1} = g(x_n)$  converges to  $x_*$  for any initial guess  $x_0 \in [a,b]$ , and the following error estimate holds

$$|x_n - x_*| \le k^n |x_0 - p|.$$

The number of iterations required to reduce the error by a factor of 10 is at most

$$\left[-\frac{1}{\log_{10}k}\right] + 1.$$

Other acceptable error estimates are

$$|x_n - x_*| \le k^n \max\{x_0 - a, \ b - x_0\},\$$

and

$$|x_n - x_*| \le \frac{k^n}{1 - k} |x_1 - x_0|.$$

Function  $g(x) = x^2 + \frac{3}{16}$  has two fixed points

$$x_1 = \frac{1}{4}$$
 and  $x_2 = \frac{3}{4}$ .

Since  $g'(x_2) = 2x_2 = \frac{3}{2} > 1$ , the assumption  $|g'(x)| \le k < 1$  of the fixed point theorem is not satisfied, and the theorem can not be applied for the fixed point  $x_2$ . Therefore, fixed point iteration is not guaranteed to converge to  $x_2$ .

We now show that function g(x) satisfies the assumptions of the fixed point theorem for a fixed point  $x_* = x_1 = \frac{1}{4}$  on the interval  $[0, \frac{3}{8}]$ . Since  $g(0) = \frac{3}{16} < \frac{3}{8}$ ,  $g(\frac{3}{8}) = \frac{21}{64} < \frac{3}{8}$ , and  $g'(x) \ge 0$  for  $x \in [0, \frac{3}{8}]$ , we have  $g([0, \frac{3}{8}]) \in [0, \frac{3}{8}]$ . Function g(x) is continuously differentiable on the interval  $[0, \frac{3}{8}]$ , and

$$\max_{[0,\frac{3}{8}]} |g'(x)| = \max_{[0,\frac{3}{8}]} (2x) = (2)\frac{3}{8} = \frac{3}{4} < 1.$$

Applying the fixed point theorem with  $k = \frac{3}{4}$ , conclude that fixed point iterations converge to the fixed point  $x_* = \frac{1}{4}$  for any initial guess  $x_0 \in [0, \frac{3}{8}]$ . The number of iterations to reduce the initial error by a factor of 10 is at most

$$\left[-\frac{1}{\log_{10} k}\right] + 1 = \left[-\frac{1}{\log_{10} \frac{3}{4}}\right] + 1 = 8 + 1 = 9.$$

#### Problem 6.

- a) Describe the power method for computing the dominant eigenvalue and a corresponding eigenvector of a matrix.
- b) Find the eigenvalues and eigenvectors of the matrix

$$A = \left(\begin{array}{cc} 6 & 4\\ 4 & 6 \end{array}\right)$$

Is the matrix semi-simple (diagonalizable)? Does it have a dominant eigenvalue?

- c) Demonstrate convergence of the power method by performing four iterations on matrix A with the initial guess  $v = (1, 0)^T$ .
- d) Compute the relative errors of the obtained approximations using the  $\infty$ -norm.

#### Solution.

a) The power method iterations are formulated as follows:

$$v_{k+1} = \frac{1}{\sigma_{k+1}} A v_k,$$

where the scaling factor  $\sigma_{k+1}$  is the entry of  $Av_k$  with the largest magnitude.

b) Eigenvalues and the corresponding eigenvectors of matrix A are

$$\lambda_1 = 10, \ \lambda_2 = 2,$$

and

$$v_1 = \begin{pmatrix} 1\\1 \end{pmatrix}$$
 and  $v_2 = \begin{pmatrix} 1\\-1 \end{pmatrix}$ 

Since A is  $2 \times 2$ , and it has two distinct eigenvalues, the matrix A has two linearly independent eigenvectors; hence, A is semi-simple. In fact, A is diagonalizable; that is, semi-simple, because it is symmetric:  $A^T = A$ . Since  $\lambda_1 > \lambda_2$ ,  $\lambda_1 = 10$ is the dominant eigenvalue of A, and  $v_1 = (1, 1)^T$  is a corresponding dominant eigenvector.

c) Performing iterations with a given matrix A and the initial guess v, obtain

k	$\sigma_k$	$(v_k)_2$
0	1	0
1	6	0.6666666666666667
2	8.6666666666666666	0.923076923076923
3	9.692307692307693	0.984126984126984
4	9.936507936507937	0.996805111821086

In the table,  $(v_k)_2$  is the second entry of the k-approximation to a dominant eigenvector  $v = (1, 1)^T$ .

d) The relative errors are

and

$$\lambda_1: \frac{|10 - 9.936507936507937|}{10} \approx 0.006349$$
$$v_1: \frac{|1 - 0.996805111821086|}{1} \approx 0.003195$$